

Neural Network Control on the Acoustic Field in a Duct

Kuo-tsai Chen, Bore-chien Tsai, Sue-min Huang, Jean-Hong Chou, Su-Hua Chang

Department of Engineering Science and Ocean Engineering, National Taiwan University

1 sect.4 Roosevelt Rd., Taipei, R.O.C. in Taiwan

E-mail: ktchen@ccms.ntu.edu.tw

ABSTRACT

This paper is a new try to the study on the active noise control in duct by combining a control theory with an artificial-intelligence neural network (AINN).

The convergence of acoustic field being actively controlled in duct by computer simulation is firstly investigated. Using the result as obtained can obtain the optimum parameter of the artificial neural network used for the required experiment.

In experiment, two setups are adopted. The first one takes the signals directly from the function generator as the reference input of the control system. The result reveals the attenuation by more than 25 and 20 dB in residual acoustic pressure and its associated power for pure- and dual-tone sounds. The second one places the reference microphone in a passive device to directly measure the signal downstream the primary source. The device as above mainly alleviates the influence of the acoustic feedback produced by the secondary source on the input microphone. Its experimental result shows the reduction by more than 30 or 20 dB for the same acoustic quantities as that of the first one.

INTRODUCTION

Regarding the noise control in the application of acoustics, it is from past studies¹⁻⁸ to show that the active control technique can provide better effectiveness than the passive one at lower frequency. Specially speaking to the active control of sound propagation in duct, the past studies involved²⁻⁹ revealed that the combination of either an adaptive or a robust control with some appropriate algorithms was usually used for getting better control effectiveness.

In recent years, the theory and applications of neural networks¹⁰⁻²⁰ for various kinds of fields, which include industrial control systems, artificial intelligence in engineering design, and economics and management science, etc., are, respectively, developed. Taking the application of neural network control to duct acoustics into consideration, Chou²¹ started the study involved in his master thesis. In this paper, it intends to study the active noise control in duct by combining a control theory with an artificial-intelligence neural network (AINN). The contents of study include the determination of optimum parameters for the artificial neural network to be used and

the required experiment. From the experimental result as obtained, it shows the two frameworks adopted for reducing acoustic feedback provide almost the same attenuation of at least 20 decibels in acoustic downstream power.

THEORETICAL BACKGROUND

From the text of acoustics¹, the acoustic pressure generated by a point source in a duct of diameter smaller than that for cutoff frequency¹ must be of plane wave type, and can be expressed in terms of either a forward or a backward going plane wave fields as:

$$p(x) = \frac{\rho_o c_o q e^{-jk|x-x_o|}}{2S} \quad (1)$$

Where ρ_o , c_o are, respectively, the density of ambient air and the speed of sound propagating through it. x_o is the position where the point source locates, q is its source strength, and S is the cross-sectional area of the duct to be adopted. When a primary source of strength q_p and a secondary source of strength q_s are placed at $x = 0$ and $x = l$, respectively. The resulting acoustic pressure is:

$$p(x) = \frac{\rho_o c_o q_p e^{-jk|x|}}{2S} + \frac{\rho_o c_o q_s e^{-jk|x-x_l|}}{2S} \quad (2)$$

As shown in Fig.1, when the strength of the two sources has the relationship of $q_s = -q_p e^{-jkl}$, the acoustic field downstream the secondary source must be a silence zone. Using the Fourier transform in real-time domain on the strength relationship as above between two sources can obtain:

$$q_s(t) = -q_p \left(t - \frac{l}{c_o} \right) \quad (3)$$

In order to eliminate the acoustic pressure downstream the secondary source, eqn(3) tells us that the secondary source must be the same strength but $\frac{l}{c_o}$ time delay as that of the primary source. Regarding the acoustic field upstream the secondary source, should be an acoustic feedback field to the primary source. In order to greatly reduce the inefficient influence of acoustic feedback as described to the control effectiveness, two specially designed frameworks of passive type are used for the experiment required for this study.

From the text of neural network¹⁰, and some past studies⁹⁻²⁰, the neural network has some special properties such as non-linearity, adaptivity, learning, memory and fault tolerance are included. Following Chou's thesis²¹, this study adopts the back-propagation neural network and its associated error algorithm as the required ones. Figs.2 shows the description to the back-propagation neural network to be adopted. By the similar manner of derivation as that of Chou's study²¹, the output u_j of j -th neuron in the output layer as shown in Fig.2 can be expressed as:

$$u_j = f(\text{net}_j) \quad (4)$$

In eqn(4), f is the activation function of neuron, which is a hyperbolic function in this study, $\text{net}_j = \sum_h (w_{hj} \cdot \text{hid}_h) + \theta_j$ is the input of j -th neuron, w_{hj} and θ_j are the associated weighting parameter and bias. Furthermore, $\text{hid}_h = f(\text{net}_h)$ is the output of the h -th neuron, $\text{net}_h = \sum_i (w_{ih} \cdot x_i) + \theta_h$ is its corresponding input, and w_{ih} , θ_h are the associated weighting parameter and bias. Generally, the real output u_j of a neural network is always not coincident with its desired output t_j , the error function E between them can be defined as:

$$E = \frac{1}{2} \sum_j (t_j - u_j)^2 \quad (5)$$

Using the steepest gradient method for the error back-propagation algorithm to minimize eqn(5), and after some complicate manipulations, either the modified weighting coefficients or the associated bias at any instant $(t+1)$ from the h -th neuron in hidden layer to the j -th neuron in the output layer can be expressed in terms of those one at earlier time t as :

$$w_{hj}(t+1) = w_{hj}(t) + \eta \delta_j \text{hid}_h \quad (6)$$

$$w_{ih}(t+1) = w_{ih}(t) + \eta \delta_h x_i \quad (7)$$

$$\theta_j(t+1) = \theta_j(t) - \eta \delta_j \quad (8)$$

$$\theta_h(t+1) = \theta_h(t) - \eta \delta_h \quad (9)$$

η is the learning rate of the neural network, $\delta_{j,h} = (t_{j,h} - u_{j,h})(1 + u_{j,h})(1 - u_{j,h})$.

To get better control effectiveness, a framework for special learning, which is shown in Fig.3, can on-line and in real time modify the weighting coefficients of the adopted back-propagation neural network. Upon the discussion as above, we can apply the back-propagation neural network with special learning framework to the active noise

control in duct. Fig.4 shows the corresponding sketch.

EXPERIMENT and RESULTS

This study is a new try to combine a back-propagation neural network with its associated error algorithm for the active acoustic control in a duct. Fig.5 shows the corresponding setup for the active-neutral network control experiment. In order to eliminate the influence by the acoustic feedback from the secondary source on the reference microphone downstream the primary source, a passive device, also shown in Fig.5, is adopted. The equipments involved in Fig.5 are all the same as that for Chou's study²¹, the illustration for them in detail are not discussed in this paper. After some trial and error for pure-tone sound, it is decisively to select the optimum values of learning rate $\eta = 0.01$, of initial weighting coefficient $w_{ij}(0) = w_{ih}(0) = 0.01$, of initial bias $\theta_j(0) = \theta_h(0) = 0.01$, and of the respective amount $i = 6, h = 3, j = 6$ of neurons, in input, hidden and output layers for the neutral network control system adopted in experiment. Upon the equipment arrangement as shown in Fig.5, we can measure both the residual acoustic pressure and associated power downstream the secondary source when the experiment is making in progress at ten frequencies from 100 to 900 Hz. The corresponding attenuation at ten frequencies as measured are 57.4, 52.7, 54.9, 47.2, 46.5, 40.6, 40.8, 43.4, 47.6, 44.8, 36.8, 38.1 dB in residual pressure, and 40, 48, 46.5, 41.6, 44.5 33.0, 43.1, 34.5, 41.7, 37.5, 30.9, 35.9 dB in residual power. Figs. 6,7, respectively, show the residual acoustic pressures before and after active control at 100 and 800 Hz. Otherwise for dual-tone sound case, changing the respective amount of neurons, in input, hidden and output layers of the adopted back-propagation neural network to be $i = 15, h = 15, j = 15$ for getting better control effectiveness, and keeping the remaining unchanged, can make the experiment in progress at four dual- tone frequencies of 300-315, 300-350, 360-400, and 450-550 Hz. The attenuation of residual acoustic pressure at the above four frequencies are 19.6, 23.7, 27.4, and 27.7 dB.

CONCLUSIONS

From the results as measured in experiment for pure-tone sound, the back-propagation neural network system with optimum parameters and an appropriate amounts of neurons for the active control of sound transmission in duct can provide attenuation of both residual acoustic pressure and the associated power by more than 50, 40 dB at low frequency and 37, 30dB at higher frequency. Regarding the dual-tone sound, optimum parameters of the system involved are still the same, but must change

the amount of neuron to be more. The attenuation in residual pressure has the greatest value of 27.7 dB at the highest dual-tone of 450-550 Hz, and lowest value of 19.6 dB at the lowest dual-tone of 300-315 Hz.

ILLUSTRATIONS

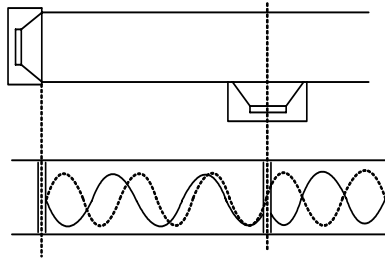


Fig.1 The acoustic interference between the fields produced by a primary and a secondary sources.

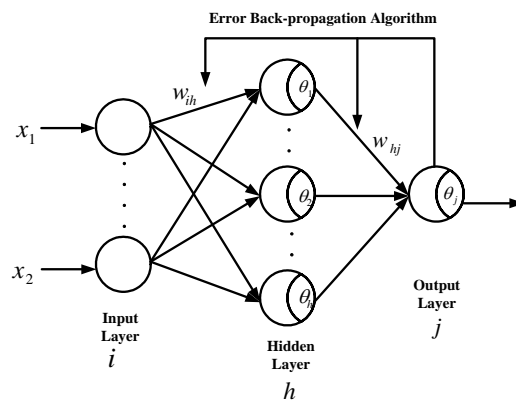


Fig. 2 Block diagram for an Error Back-propagation Neural Network

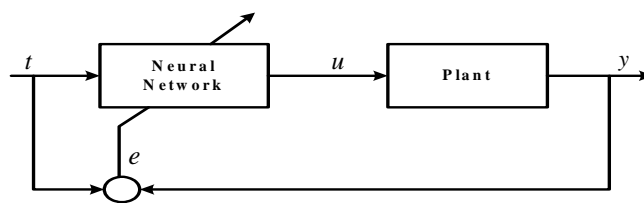


Fig.3 The block diagram of a special learning framework

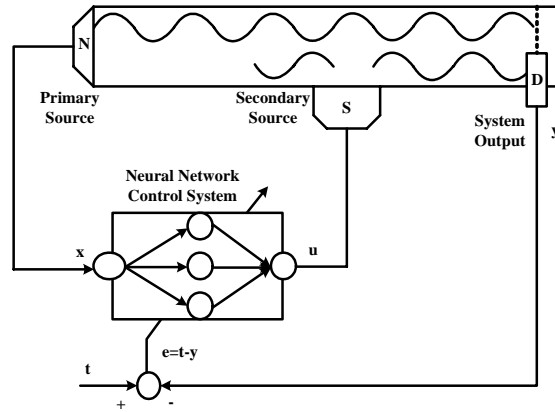


Fig.4 The sketch of a back-propagation neural network with special learning

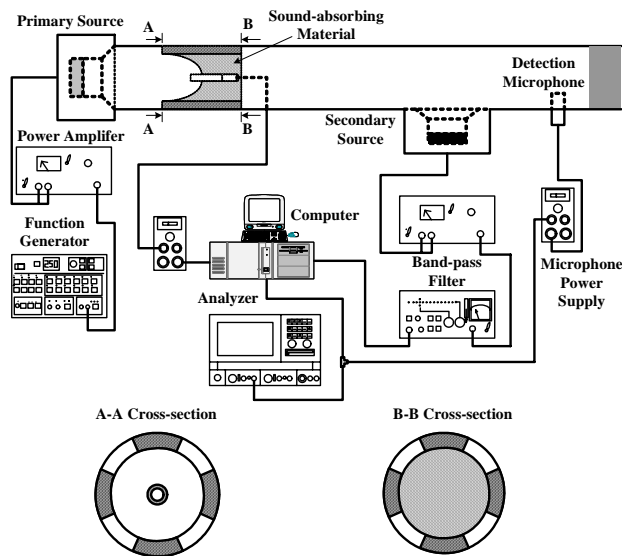


Fig.5 Setup of all equipments in the neural network control experiment.

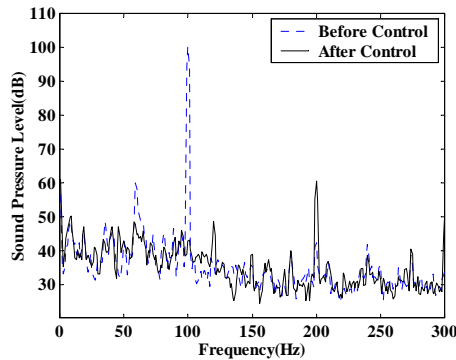


Fig. 6 The residual sound pressures at 100Hz before and after active control.

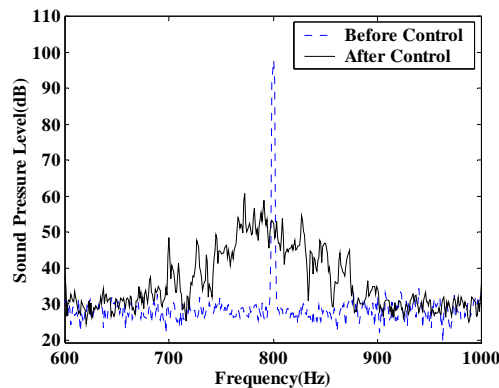


Fig.7 The residual sound pressures at 800Hz before and after active control.

REFERENCES

1. P. A. Nelson and S. J. Elliott, *Active Control of Sound*. (Academic Press, London, 1992)
2. M. Jessel and G. A. Mangiante, "Active Sound Absorbers in an Air Duct", *Journal of Sound and Vibration*, 23(3), 383-390(1972)
3. S. J. Elliot, I. M. Stothers and P. A. Nelson, "A Multiple Error LMS Algorithm and Its Application to the Active Control of Sound and Vibration", *IEEE Transactions on Acoustics, Speech and Signal Processing*, 35(4) (1987)
4. K. T. Chen, Y. N. Chen, W. Chen and Y. H. Liu, "Adaptive Active control on the Acoustic Transmission of the Acoustic Sources in Aperture at Low Frequencies", *Applied Acoustics*, 54(2), 141-164 (1998)
5. J. Hu, "Feedback and Feed-forward Control Strategy for Active Noise Cancellation in Ducts", *Journal of Dynamic Systems, Measurement and Control*, ASME, 118, 372-378(1996)
6. J. H. B. Pools and H. G. Leventhall, "An Experimental Study of Swinbanks' Method of Active Attenuation of Sound in Duct", *J. Sound & Vib.*, 49, 257-266(1976)
7. M. Berengier and A. Roure, "Broadband Active Sound Absorption in a Duct Carrying Uniformly Flowing Fluid", *J. Sound & Vib.*, 68, 437-449(1980)
8. L. J. Eriksson and M. C. Allie, "Use of Random Noise for on-line Transducer Modeling in an Adaptive Active Attenuation System", *J. Acoust. Soc. Am.*, 85(2), 797-802 (1989)
9. S. Liu, J. Yuan and K. Y. Fung, "Robust Active Noise Control in a Finite Duct by Separation of Traveling Waves", *The 8th International Congress on Sound and Vibration*, Hong Kong, China, 183-190 (2001)
10. W. S. McCulloch and W. H. Pitts, "A Logical Calculus of the Ideas Immanent in Nervous Activity", *Bull. Math. Biophysics*, 5, 115-123 (1943)
11. I. Baruch, J. M. Flores, F. Thomas and R. Garrido, "Adaptive Neural Control of Nonlinear Systems", *ICANN* (2001)

12. N. S. Philip and K. B. Joseph, "Adaptive Basis Function for Artificial Neural Networks", *Neurocomputing*, 47, 21-34 (2002)
13. S. Hayken, *Neural Networks: A Comprehensive Foundation* (New York: Macmillan, 1992)
14. T. Fukuda and T. Shibata, "Theory and Applications of Neural Networks for Industrial Control Systems", *IEEE Transactions on Industrial Electronics*, 39(6) (1992)
15. D. Psaltis, A. Sideris and A. A. Yamamura, "A Multi-layered Neural Network Controller", *IEEE Control Systems Magazine*, 17-21(1988)
16. I. Kaastra and M. Boyd, "Designing a Neural Network for Forecasting Financial and Economic Time Series", *Neurocomputing*, 10, 215-236(1996)
17. C. T. Lin and C. S. G. Lee, *Neural Fuzzy systems: A Neural-Fuzzy Synergism to Intelligent Systems*, NJ: Prentice Hall (1996)
18. D. Parker," Learning-Logic, Center for Computational Research in Economics and Management Science, M.I.T., TR47, Cambridge, MA (1985)
19. F. Rosenblatt, "The Perceptron: A Probabilistic Model for Information Storage and Organization in the Brain," *Psychological Rev.*, 65, 368-408 (1958)
20. F. C. Chen, "Back-Propagation Neural Networks for Nonlinear Self-Tuning Adaptive Control", *IEEE Control Systems Magazine*, 44-48(1990)
21. Jean-Hong Chou, "Neural Network Control on the Acoustic Field in a Duct," Master thesis, ESOE, National Taiwan University (2003)